

# Lecture 4

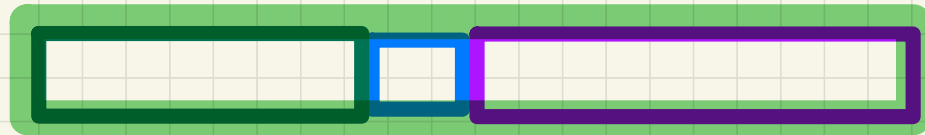
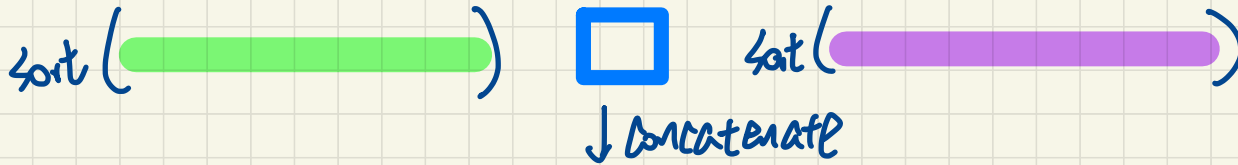
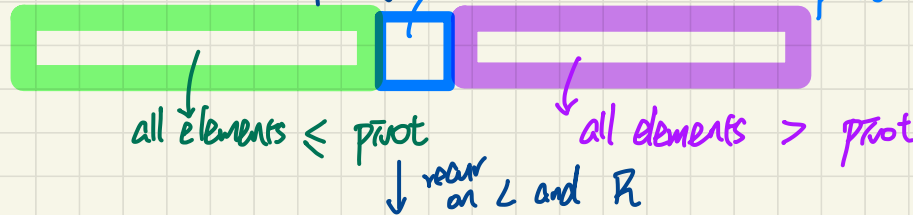
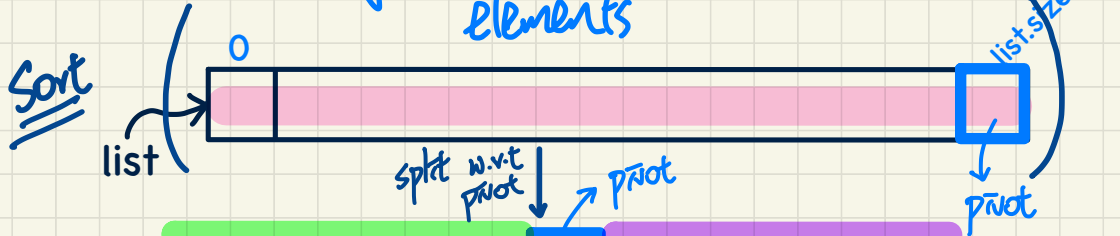
## Part D

***Examples on Recursion***  
***Quick Sort***

# Quick Sort: Ideas



pivot: ideally the median value of the list elements



Sorted version of input list.

# Quick Sort in Java

```

public List<Integer> sort(List<Integer> list) {
    List<Integer> sortedList;
    if(list.size() == 0) { sortedList = new ArrayList<>(); }
    else if(list.size() == 1) {
        sortedList = new ArrayList<>(); sortedList.add(list.get(0));
    }
    else {
        int pivotIndex = list.size() - 1;
        int pivotValue = list.get(pivotIndex);
        List<Integer> left = allLessThanOrEqualTo(pivotIndex, list);
        List<Integer> right = allLargerThan(pivotIndex, list);
        List<Integer> sortedLeft = sort(left);
        List<Integer> sortedRight = sort(right);
        sortedList = new ArrayList<>();
        sortedList.addAll(sortedLeft);
        sortedList.add(pivotValue);
        sortedList.addAll(sortedRight);
    }
    return sortedList;
}
    
```

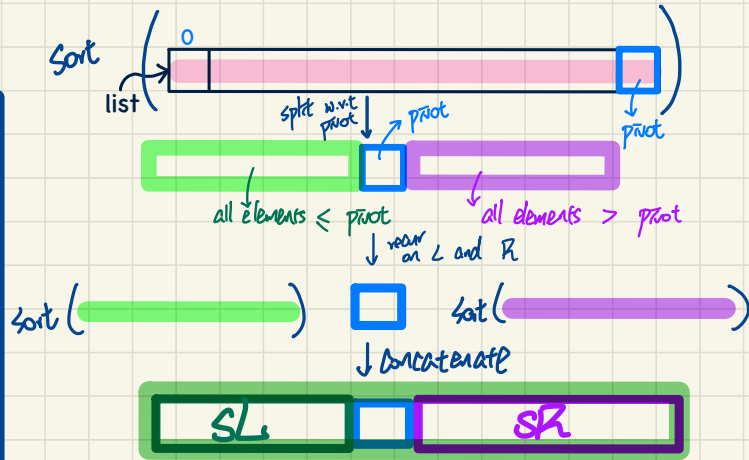
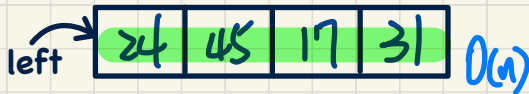
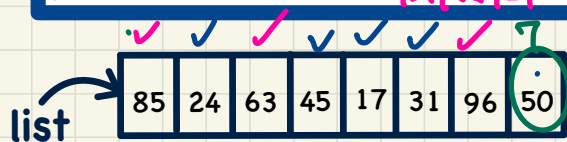
*base cases*

*0(1)*

*1. Best case: pivot is st. |L| ≈ |R|*

*2. Worst case: |L| << |R| or |R| << |L|*

*OLN*



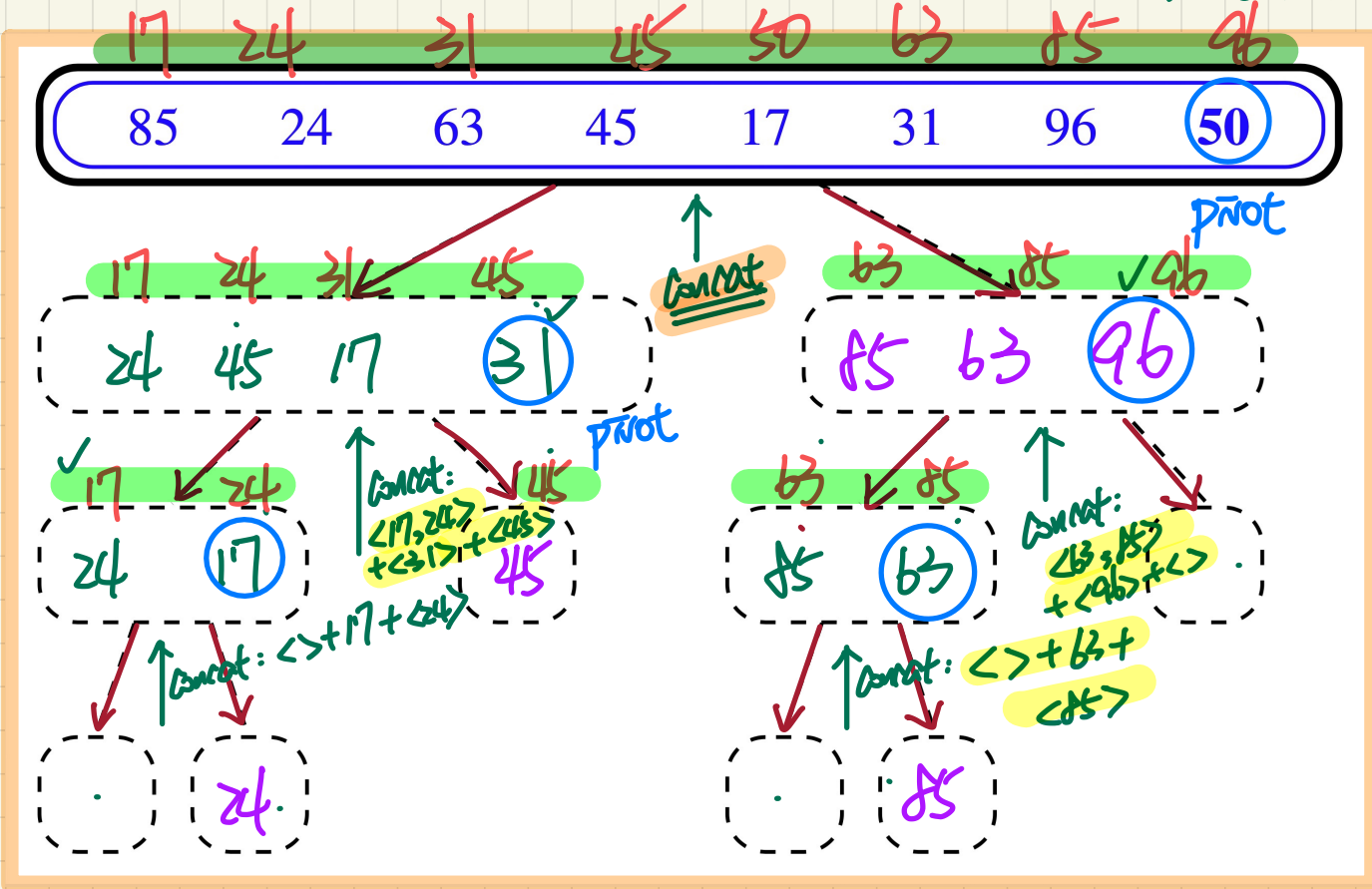
```

List<Integer> allLessThanOrEqualTo(int pivotIndex, List<Integer> list) {
    List<Integer> sublist = new ArrayList<>();
    int pivotValue = list.get(pivotIndex);
    for(int i = 0; i < list.size(); i++) {
        int v = list.get(i);
        if(i != pivotIndex && v <= pivotValue) { sublist.add(v); }
    }
    return sublist;
}

List<Integer> allLargerThan(int pivotIndex, List<Integer> list) {
    List<Integer> sublist = new ArrayList<>();
    int pivotValue = list.get(pivotIndex);
    for(int i = 0; i < list.size(); i++) {
        int v = list.get(i);
        if(i != pivotIndex && v > pivotValue) { sublist.add(v); }
    }
    return sublist;
}
    
```

# Quick Sort: Tracing

→ split  
→ concatenate



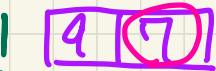
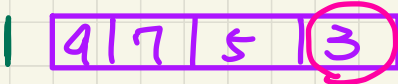
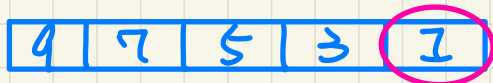
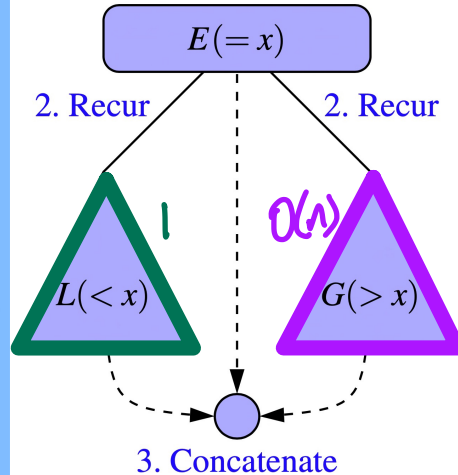
# Quick Sort: Worst-Case Running Time

```

public List<Integer> sort(List<Integer> list) {
    List<Integer> sortedList;
    • if(list.size() == 0) { sortedList = new ArrayList<>(); }
    • else if(list.size() == 1) {
        sortedList = new ArrayList<>(); sortedList.add(list.get(0)); }
    else {
        int pivotIndex = list.size() - 1;
        int pivotValue = list.get(pivotIndex);
        List<Integer> left = allLessThanOrEqualTo(pivotIndex, list);
        List<Integer> right = allLargerThan(pivotIndex, list);
        List<Integer> sortedLeft = sort(left);
        List<Integer> sortedRight = sort(right);
        sortedList = new ArrayList<>();
        sortedList.addAll(sortedLeft);
        sortedList.add(pivotValue);
        sortedList.addAll(sortedRight);
    }
    return sortedList;
}
    
```

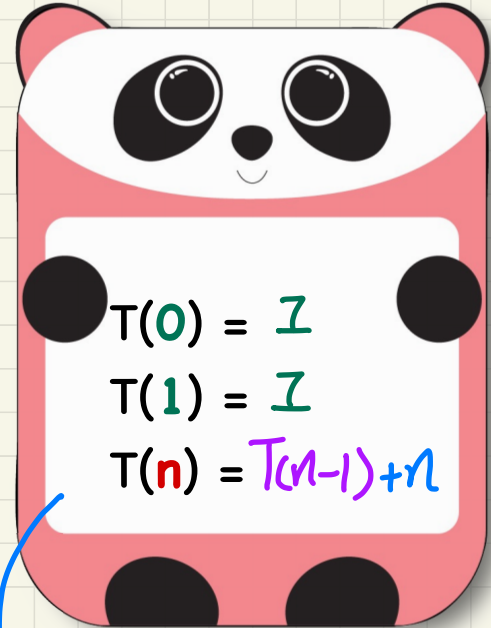
$O(n)$

1. Split using pivot  $x$



# splits:  
4  $O(n)$

## Running Time as a Recurrence Relation



$$T(0) = 1$$

$$T(1) = 1$$

$$T(n) = T(n-1) + n$$

Exercise: Solve by unrolling

# Quick Sort: Best-Case Running Time

log<sub>2</sub>n

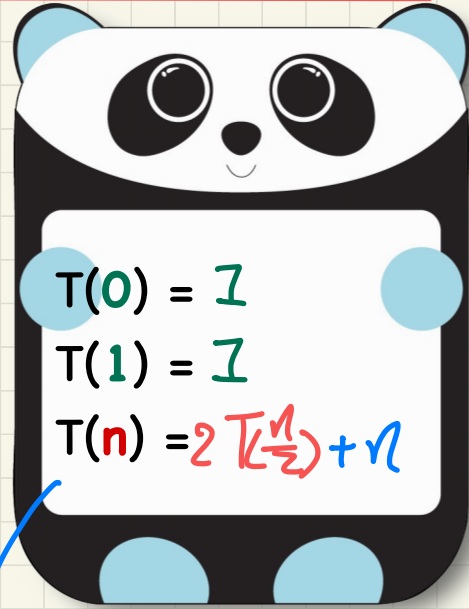
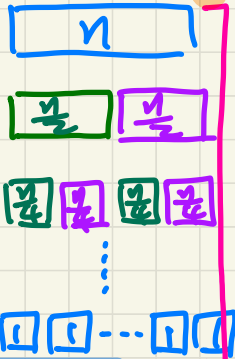
Running Time as a Recurrence Relation

```

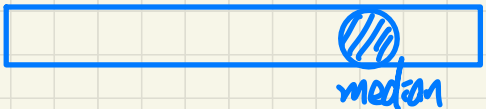
public List<Integer> sort(List<Integer> list) {
    List<Integer> sortedList;
    if(list.size() == 0) { sortedList = new ArrayList<>(); }
    else if(list.size() == 1) {
        sortedList = new ArrayList<>(); sortedList.add(list.get(0));
    }
    else {
        int pivotIndex = list.size() - 1;
        int pivotValue = list.get(pivotIndex);
        List<Integer> left = allLessThanOrEqualTo(pivotIndex, list);
        List<Integer> right = allLargerThan(pivotIndex, list);
        List<Integer> sortedLeft = sort(left);
        List<Integer> sortedRight = sort(right);
        sortedList = new ArrayList<>();
        sortedList.addAll(sortedLeft);
        sortedList.add(pivotValue);
        sortedList.addAll(sortedRight);
    }
    return sortedList;
}
    
```

$O(1)$

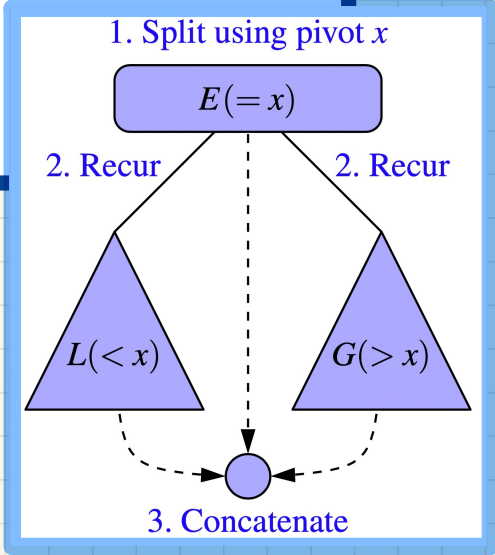
$O(n)$



$$\begin{aligned}
 T(0) &= 1 \\
 T(1) &= 1 \\
 T(n) &= 2T\left(\frac{n}{2}\right) + n
 \end{aligned}$$



sizes equal



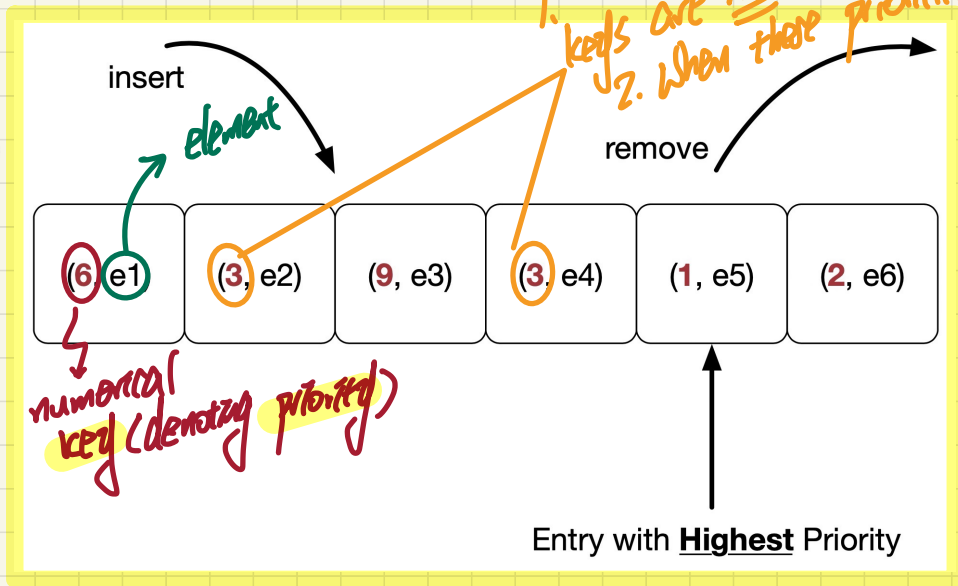
Ex. 2 Exercise: solve by Unfolding.  
 $T(0) = 1$   
 $T(1) = 1$   
 $T(n) = T\left(\frac{n}{2}\right) + T\left(\frac{n}{2}\right) + n$

# Lecture 5d

## Part A

### ***Priority Queue - Intro & List-Based Implementations***

# What is a Priority Queue (PQ)



1. keys are not for searching purpose  
2. When these priorities become the highest, it does not matter which entry is chosen.

Compare: 1. FIFO q. based on order of insertion.  
2. PQ. remove element based on chronological order of insertion.

numerical key (denoting priority)

1. In PQ, no notions of "front" or "end" of the q.
2. The lower the key value of an entry, the higher its priority is.  
↳ the entry with the minimum key value has the highest priority.



# List-Based Implementations of Priority Queue (PQ)

## EXERCISE

Use DLL for A1 & A2.  
Does it make a difference to RT?

e.g. of app has more frequent calls to "min" choice A1

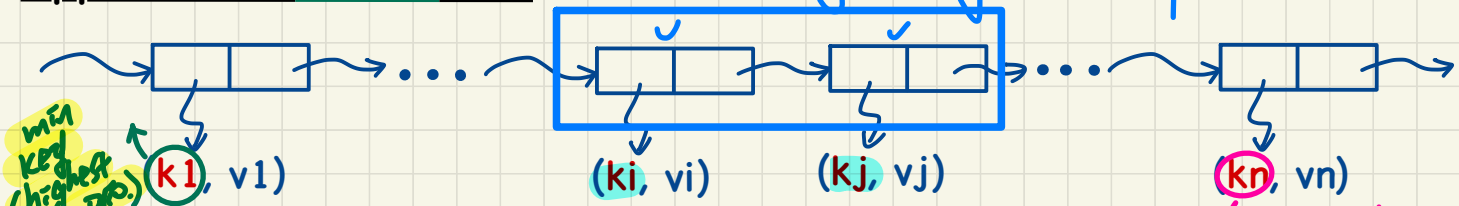
PQ Method	List Method	
	A1	A2
	<b>SORTED LIST</b>	<b>UNSORTED LIST</b>
size	list.size $O(1)$	list.size $O(1)$
isEmpty	list.isEmpty $O(1)$	list.isEmpty $O(1)$
min	list.first $O(1)$	search min $O(n)$
insert	insert to "right" spot $O(n)$	insert to front $O(1)$
removeMin	list.removeFirst $O(1)$	search min and remove $O(n)$

$\approx$  insert sort (pointing to A1)

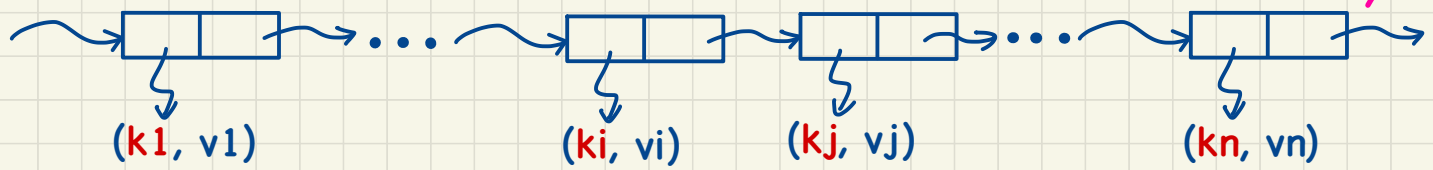
$\approx$  selection sort (pointing to A2)

### Approach 1: Sorted List

$k_i \leq k_j$  (entry  $i$  "more important" than entry  $j$ )



### Approach 2: Unsorted List



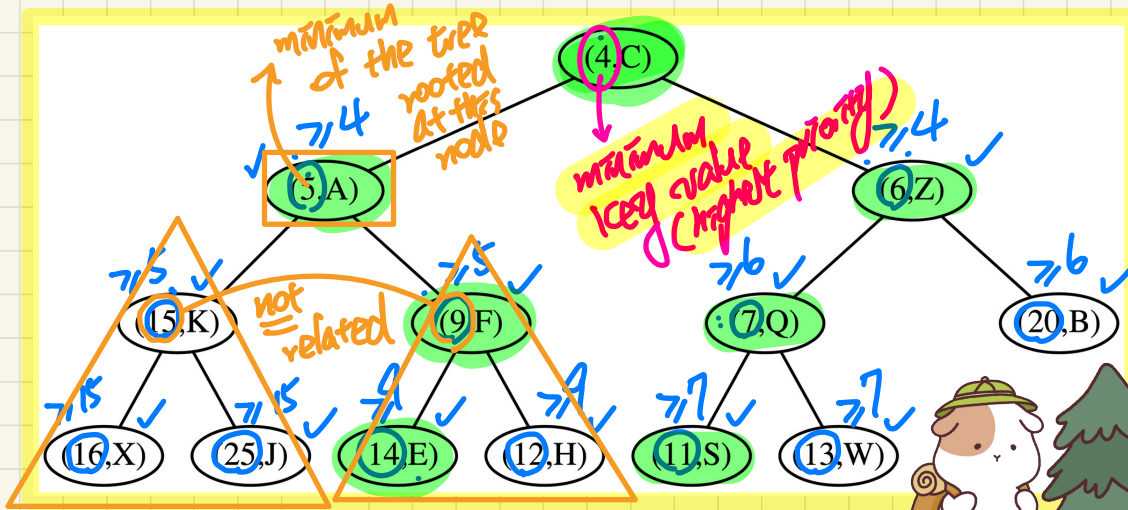
# Lecture 5d

## Part B

### *Heaps - Examples and Properties*

# Heaps: Relational Properties of Keys

**Property:** Each non-root node  $n$  is s.t.  $\text{key}(n) \geq \text{key}(\text{parent}(n))$



P1. Any leaf-to-root path has a sorted seq of keys.

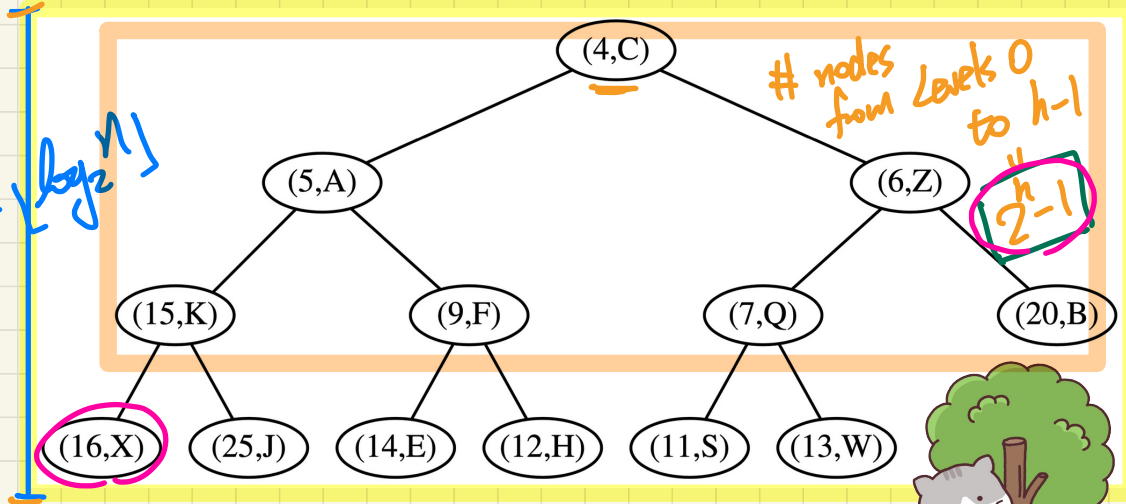
P2. the minimum key exists in the root entry.



P3. key values between LST and RST are not related.

# Heaps: Structural Properties of Nodes

Property: The tree is a complete Binary Tree



$n = 13$   
 $\lfloor \log_2 13 \rfloor = \lfloor 3.7 \dots \rfloor = 3$

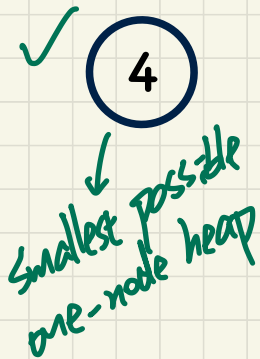
Min # of nodes:  $(2^h - 1) + 1$   
Max # of nodes:  $(2^h - 1) + 2^h$   
 $= 2^{h+1} - 1$

# of nodes at level  $h = n - (2^h - 1)$

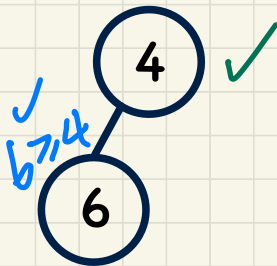


# Example Heaps < relational structural

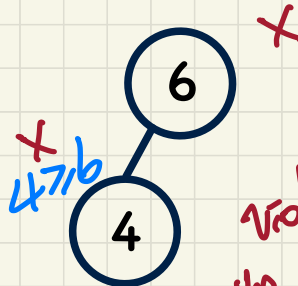
Example 1



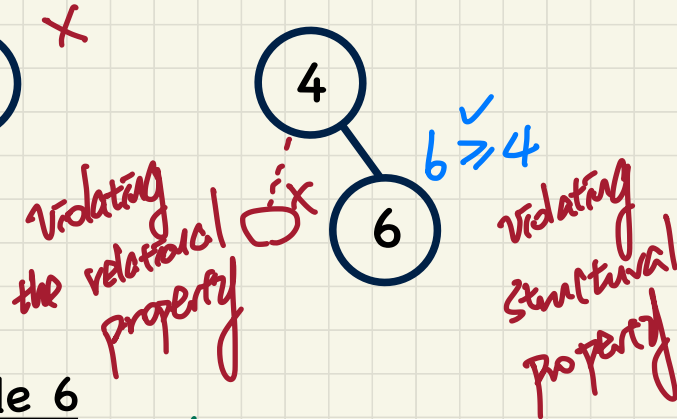
Example 2



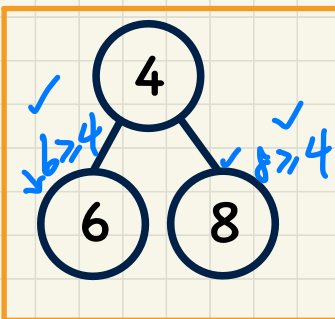
Example 3



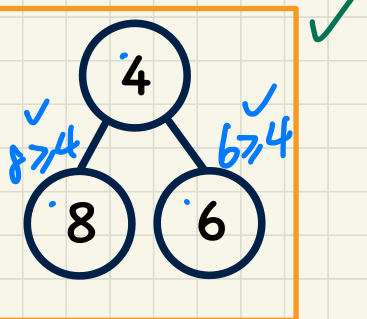
Example 4



Example 5



Example 6



Full BTs  
⇒ Complete BTs

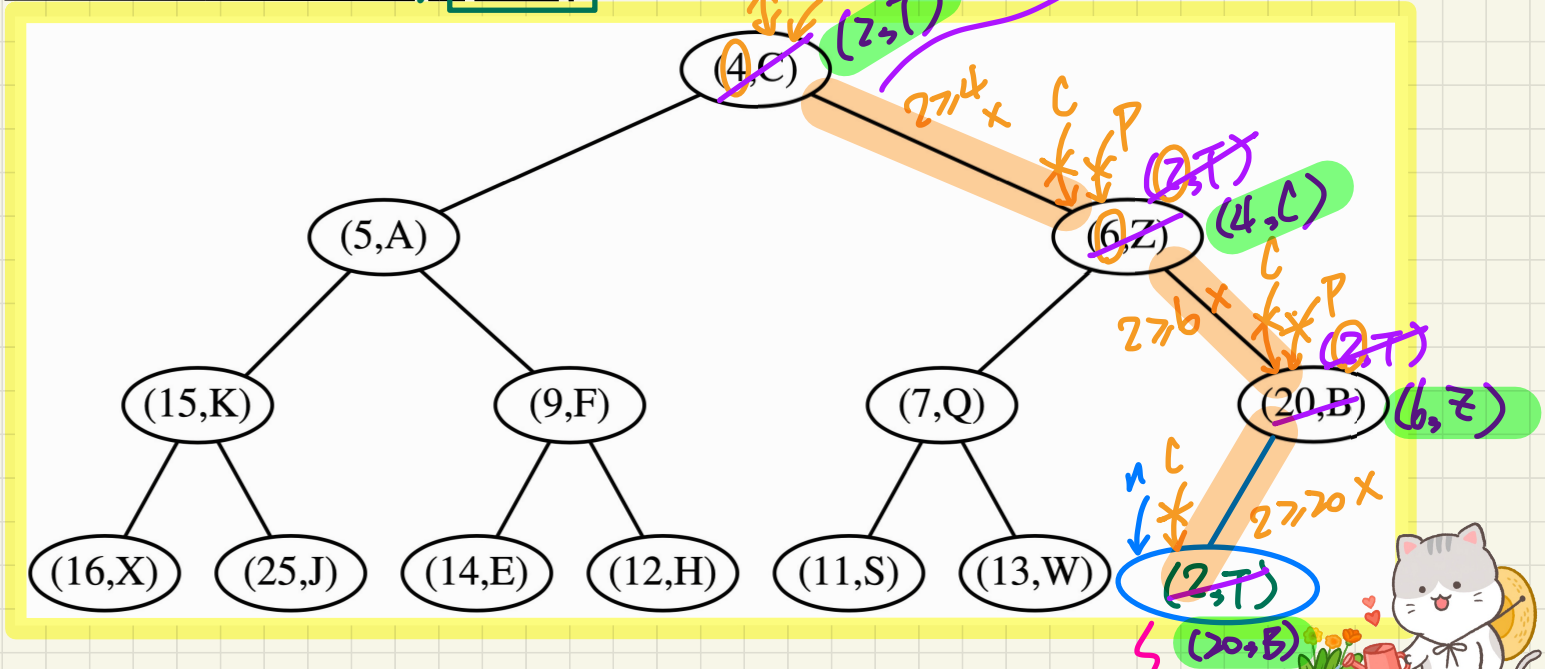
# Lecture 5d

## Part C

### *Heaps - Insertions*

# Heap Operations: Insertion

Insert a new entry (2, T) <sup>e</sup>



must be right-most at level  $h$  in order to preserve structural property



# Lecture 5d

## Part D

### *Heaps - Deletions*

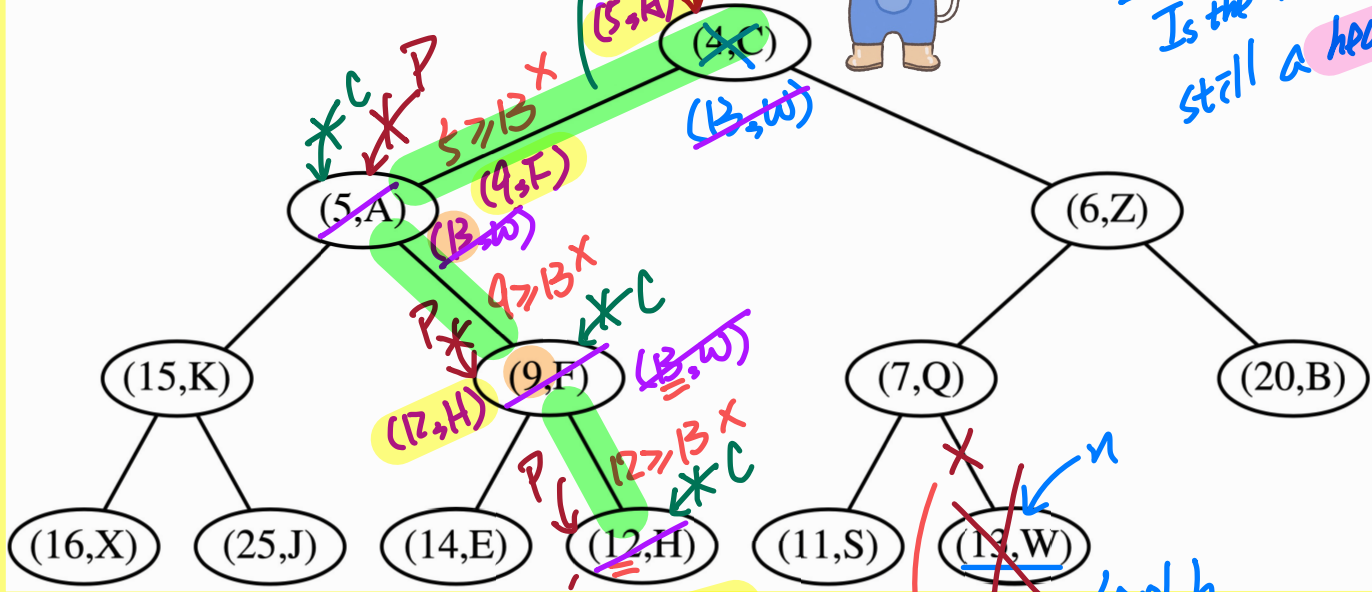


# Heap Operations: Deletion

root-to-leaf path (down-heap bubbling)

Delete the root/minimum

Exercise  
Is the resulting tree still a heap?



external node

At Level h, nodes are still filled from L to R ⇒ complete BT

# Lecture 5d

## Part E

### *Heaps - Top-Down Heap Construction*

# Top-Down Heap Construction

**Problem:** Build a heap out of  $N$  entries, supplied one at a time.

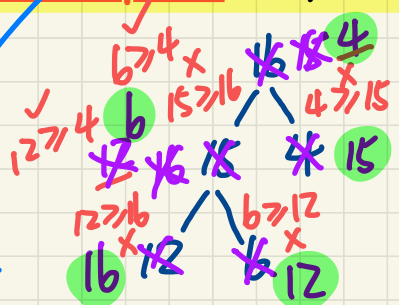
- Initialize an *empty heap*  $h$ .
- As each new entry  $e = (k, v)$  is supplied, insert  $e$  into  $h$ .

RI: # nodes at level  $i$   
 $* 1 + 2 + 2^2 + \dots + 2^h$   
 $\leq \lg_2 N$  # up-heap building steps  
 $\leq \lg_2 N$   
 $\leq \lg_2 N$   
 $\leq \lg_2 N$

**Exercise:** Build a heap out of the following 15 keys:

<16, 15, 4, 12, 6, 7, 23, 20, 25, 9, 11, 17, 5, 8, 14>

**Assumption:** Key values supplied one at a time.

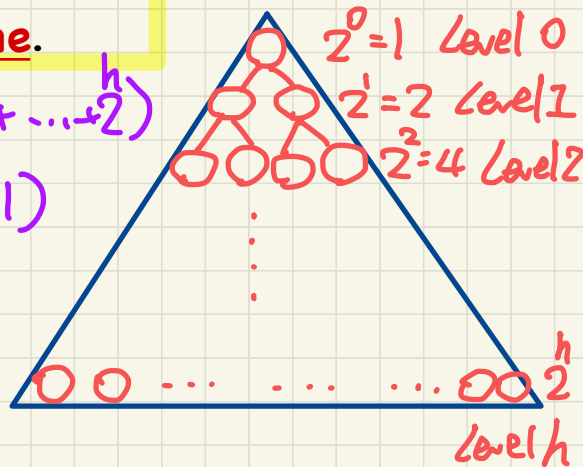


First inserted to level 1

$* \leq 1 + \lg_2 N \cdot (2^1 + 2^2 + \dots + 2^h)$   
 $= 1 + \lg_2 N (N - 1)$

$O(N \cdot \lg_2 N)$

Exercise: Complete inserting the remaining keys to the heap.



# Lecture 5d

## Part F

### *Heaps - Bottom-Up Heap Construction*

# Bottom-Up Heap Construction

**Problem:** Build a heap out of  $N$  entries, supplied all at once.

- **Assume:** The resulting heap will be **completely filled** at all levels.

$N = 2^{h+1} - 1$  for some **height**  $h \geq 1$  [  $h = (\log(N + 1)) - 1$  ]

- Perform the following steps called **Bottom-Up Heap Construction**:

**Step 1** Treat the first  $\frac{N+1}{2}$  list entries as heap roots.  
 $\therefore \frac{N+1}{2}$  heaps with height 0 and size  $2^0 - 1$  constructed.

**Step 2** Treat the next  $\frac{N+1}{2}$  list entries as heap roots.  
 ◇ Each **root** sets two heaps from **Step 1** as its **LST** and **RST**.  
 ◇ Perform **down-heap bubbling** to restore **HOP** if necessary.  
 $\therefore \frac{N+1}{2}$  heaps, each with height 1 and size  $2^2 - 1$  constructed.

**Step  $h+1$ :** Treat next  $\frac{N+1}{2^{h+1}} = \frac{(2^{h+1}-1)+1}{2^{h+1}} = 1$  list entry as heap root.  
 ◇ Each **root** sets two heaps from **Step  $h$**  as its **LST** and **RST**.  
 ◇ Perform **down-heap bubbling** to restore **HOP** if necessary.  
 $\therefore \frac{N+1}{2^{h+1}} = 1$  heap, each with height  $h$  and size  $2^{h+1} - 1$  constructed.

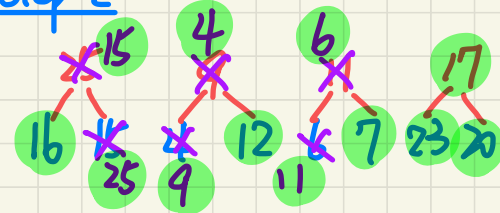
50% Step 1

8 heaps, size 1, height 0

16 15 4 12 6 7 23 20

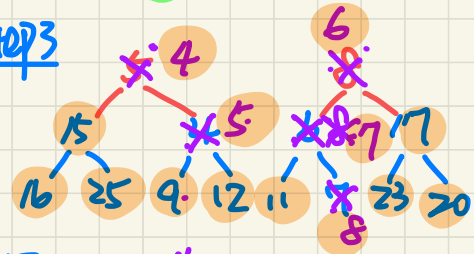
Step 2

25%

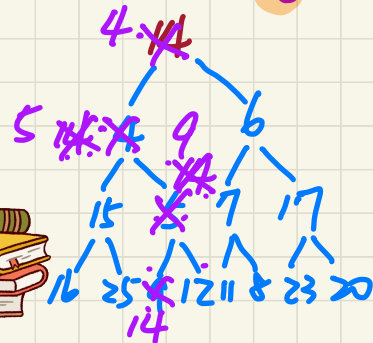


Step 3

12.5%



Step



Step 3: 8 heaps

N/8 = 2

Size of heap: 2^3 = 8

each height of each heap: 2

2

**Exercise:** Build a **heap** out of the following 15 keys:

<16, 15, 4, 12, 6, 7, 23, 20, 25, 9, 11, 17, 5, 8, 14>

**Assumption:** Key values supplied all at once.



# Lecture 5d

## Part G

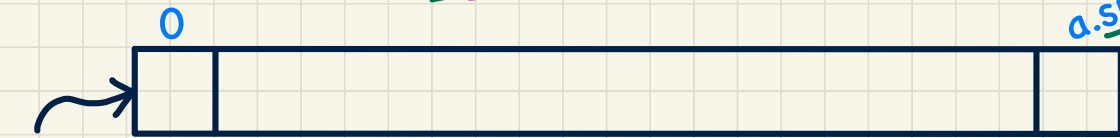
### *Heaps - Heap Sort Algorithm*

# Heap Sort: Ideas

$O(N \cdot \log N)$

$N$  entries

$a.size() - 1$

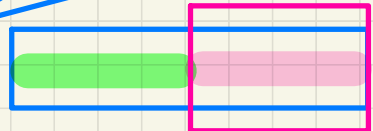


Construct a heap out of  $N$  entries

(A) Top-Down

(B) Bottom-Up

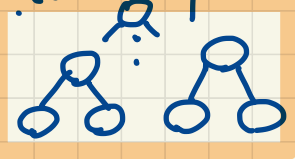
Selection Sort



select the min from unsorted portion & put it to the front/end of the list



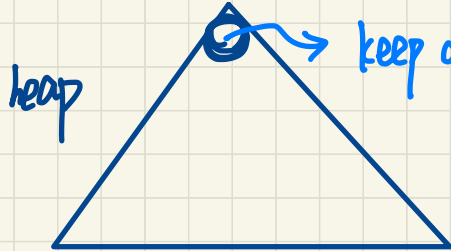
$O(N \cdot \log N)$



$O(N)$

$\approx$  Selection Sort

exploit the HOP (relational property): root stores entry with min key



keep deleting the root until the heap is empty.

$N$  deletions, each  $O(\log N) \Rightarrow O(N \cdot \log N)$

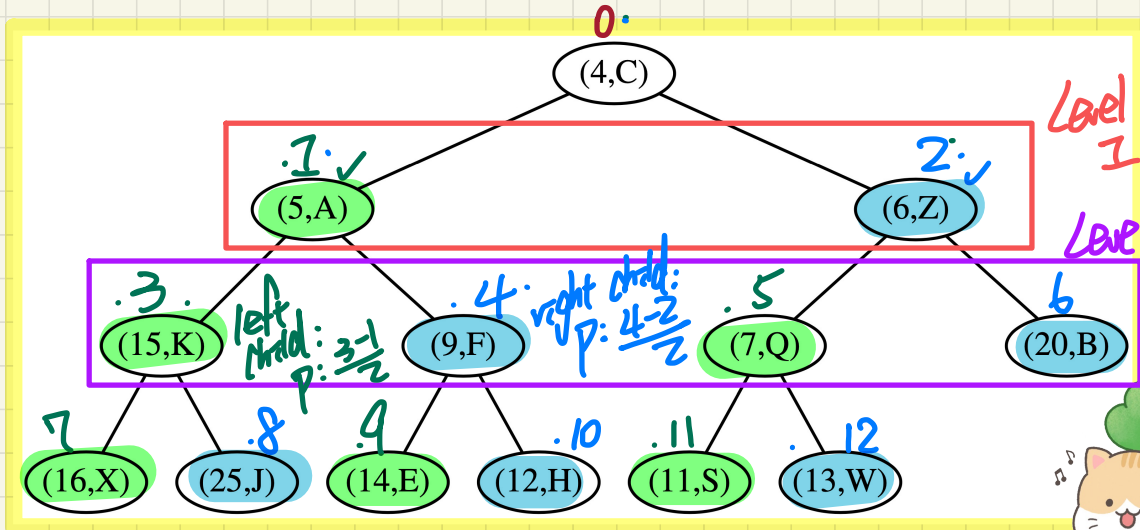
# Lecture 5d

## Part H

### *Heaps - Array-Based Implementation*



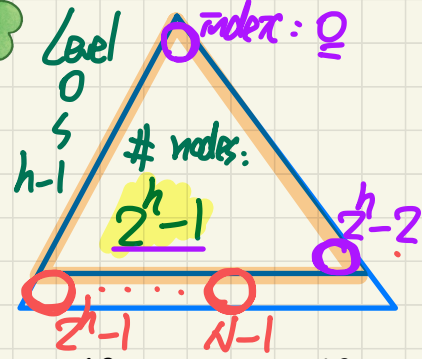
# Array-Based Representation of a Complete BT



Exercise

What if the BT is not complete? (bad for space util.)

$$index(x) = \begin{cases} 0 & \text{if } x \text{ is the root} \\ 2 \cdot index(\text{parent}(x)) + 1 & \text{if } x \text{ is a left child} \\ 2 \cdot index(\text{parent}(x)) + 2 & \text{if } x \text{ is a right child} \end{cases}$$



0	1	2	3	4	5	6	7	8	9	10	11	12
(4,C)	(5,A)	(6,Z)	(15,K)	(9,F)	(7,Q)	(20,B)	(16,X)	(25,J)	(14,E)	(12,H)	(11,S)	(13,W)